

For: System, Method And Storage Medium For Predicting Impact Performance of Painted Thermoplastic
Inventor: Joseph Thomas Woods
Docket No. 08EB03119
Cantor Colburn LLP 55 Griffin Road South, Bloomfield, CT 06002
(860) 286-2929

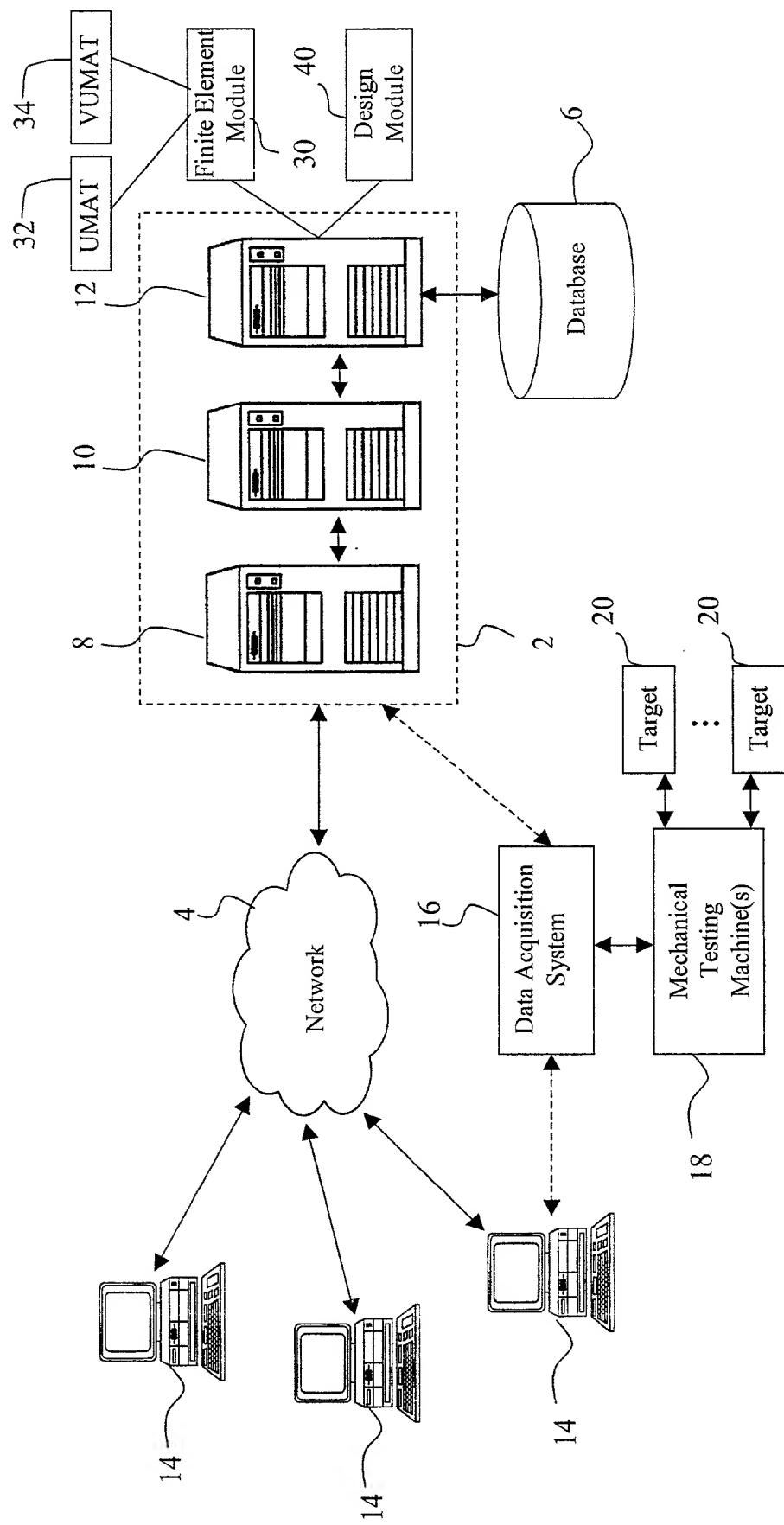


FIG. 1

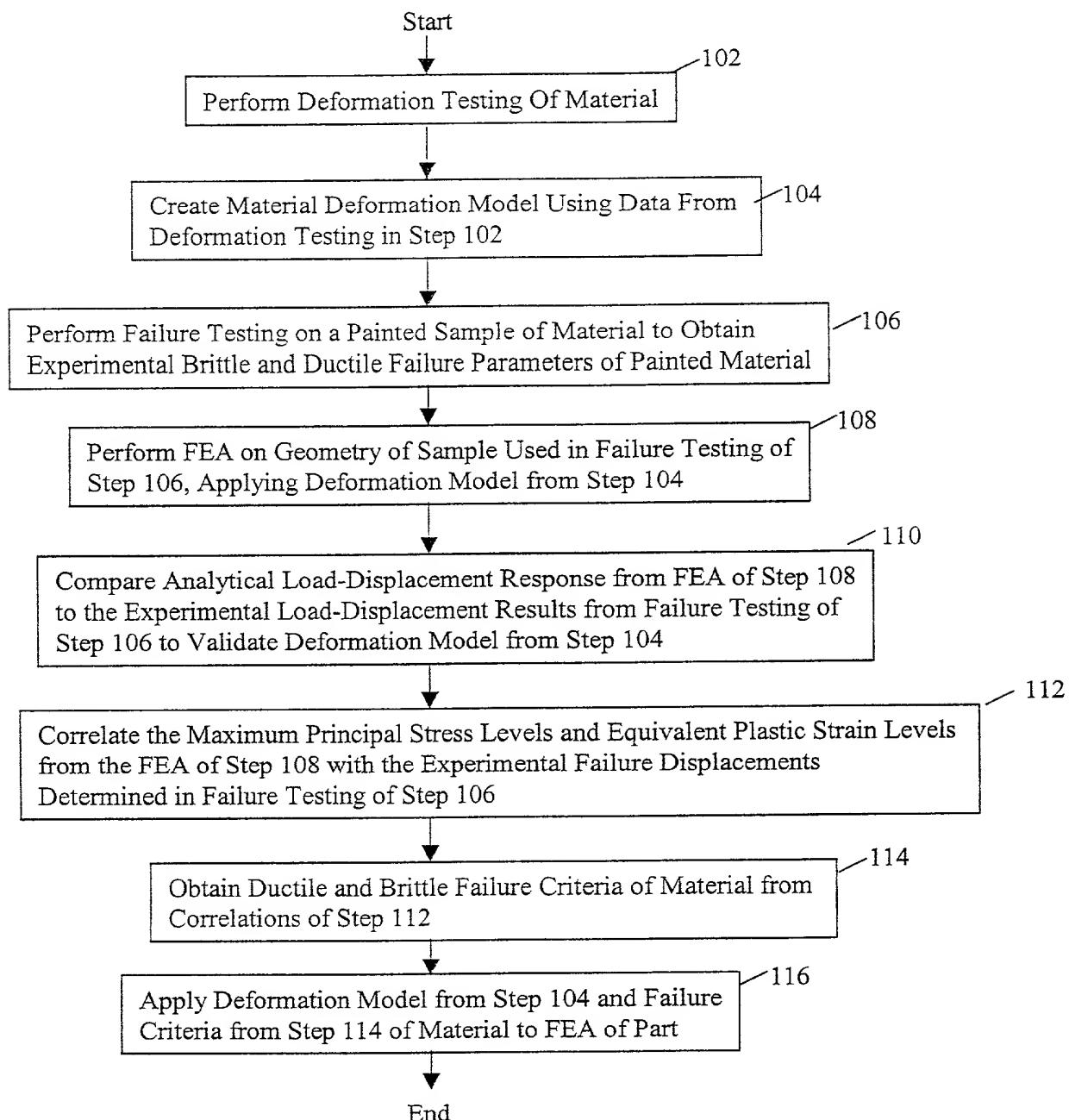


FIG. 2

100

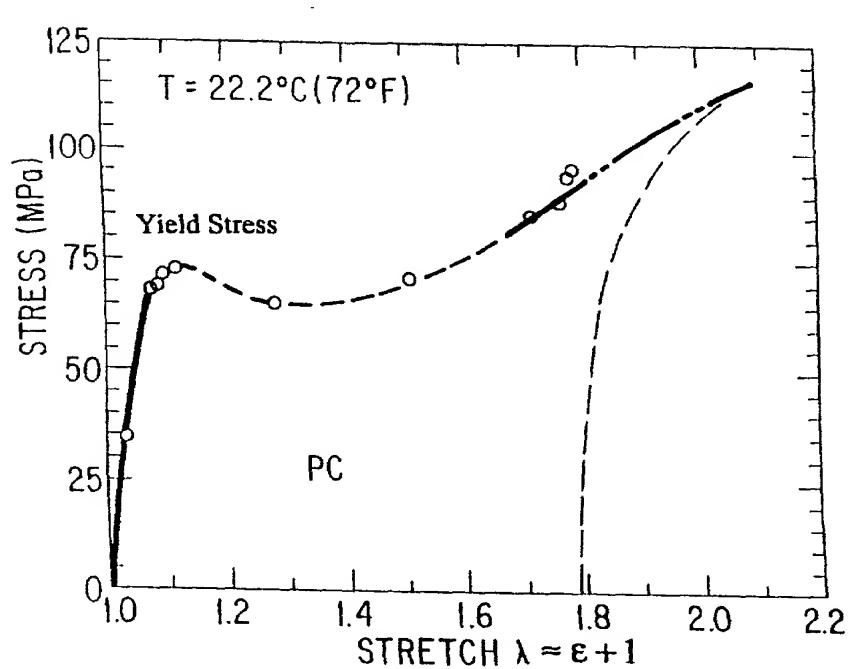


FIG. 3

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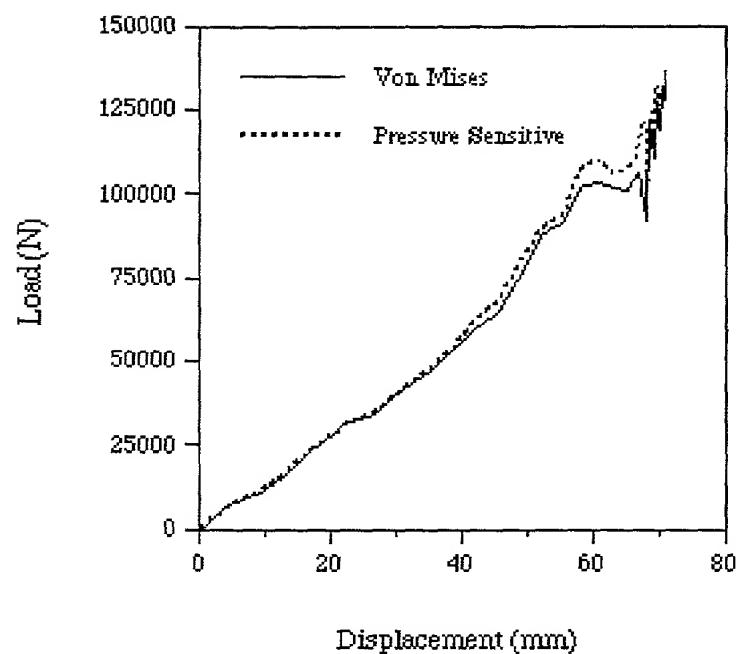


FIG. 4

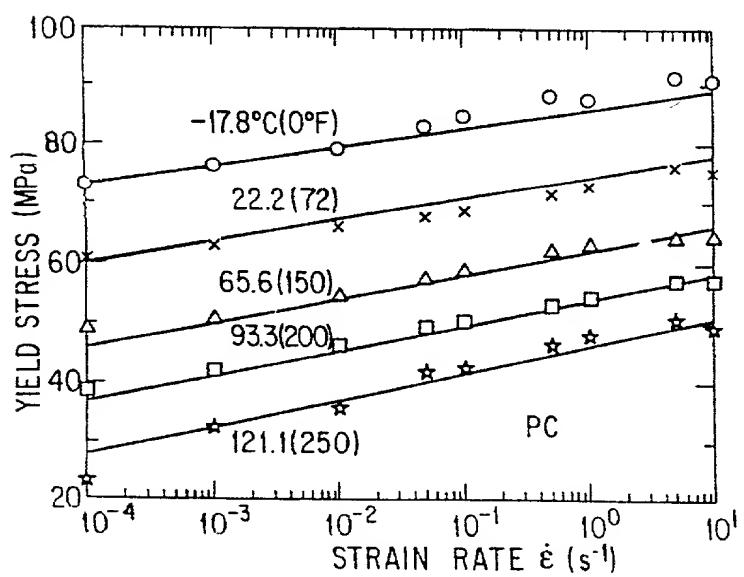


FIG. 5

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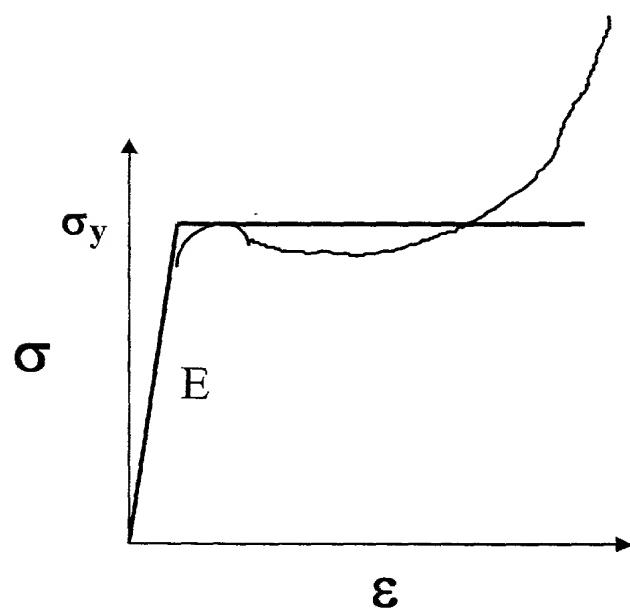


FIG. 6

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FIG. 7

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Patent No. 5,292,650

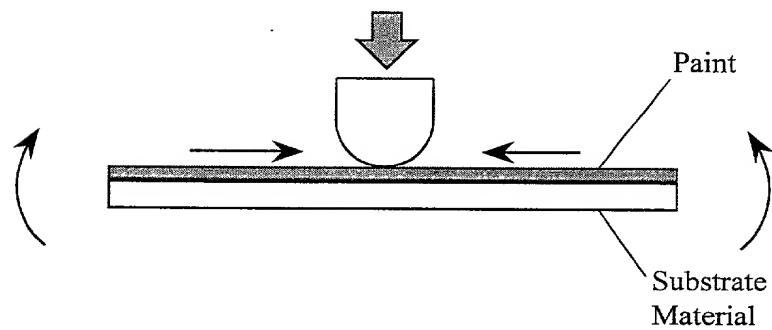


FIG. 8

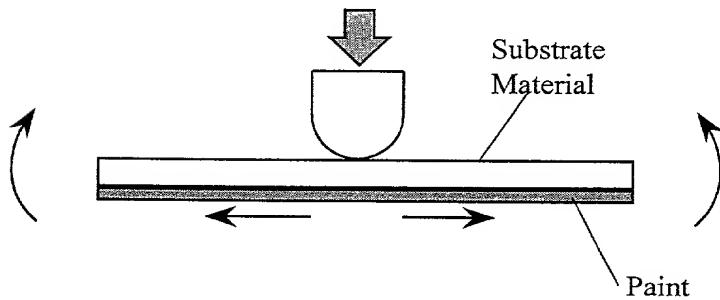


FIG. 9

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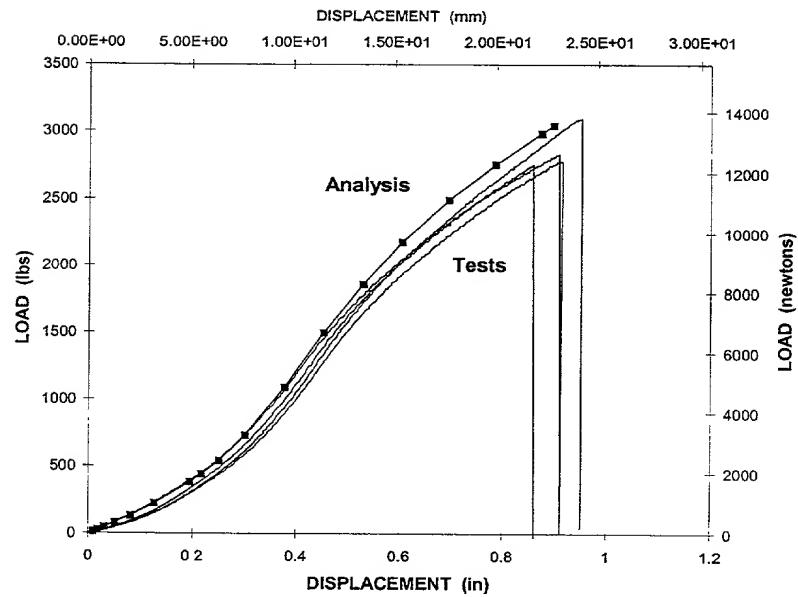


FIG. 10

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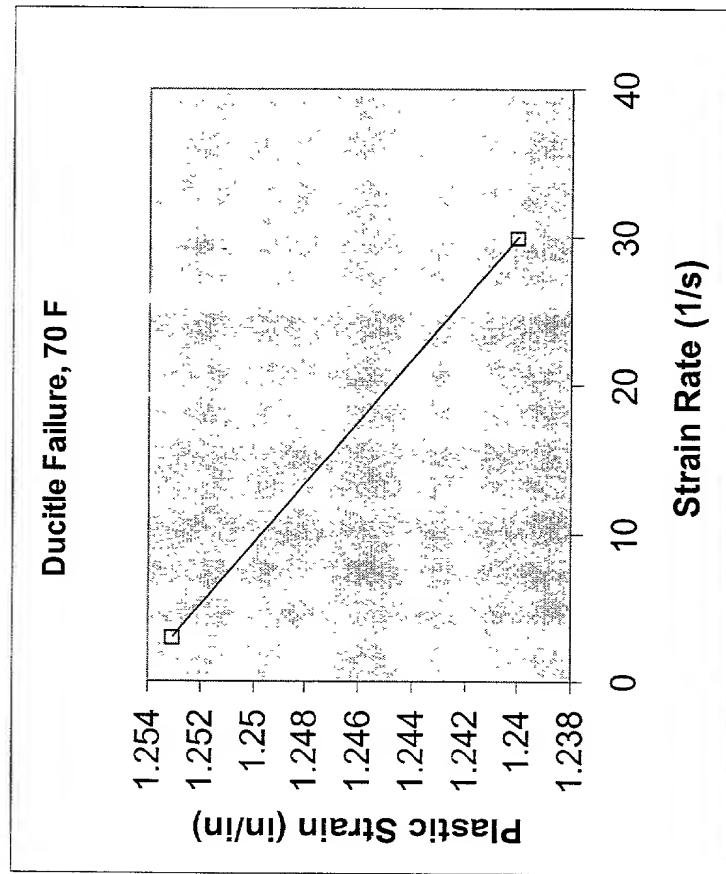


FIG. 11

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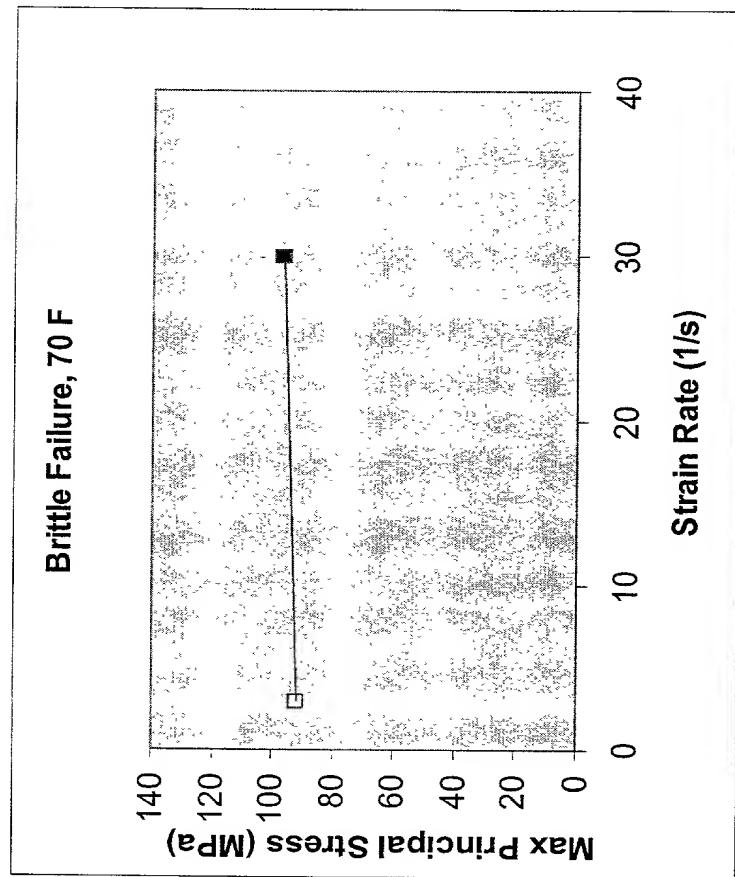


FIG. 12

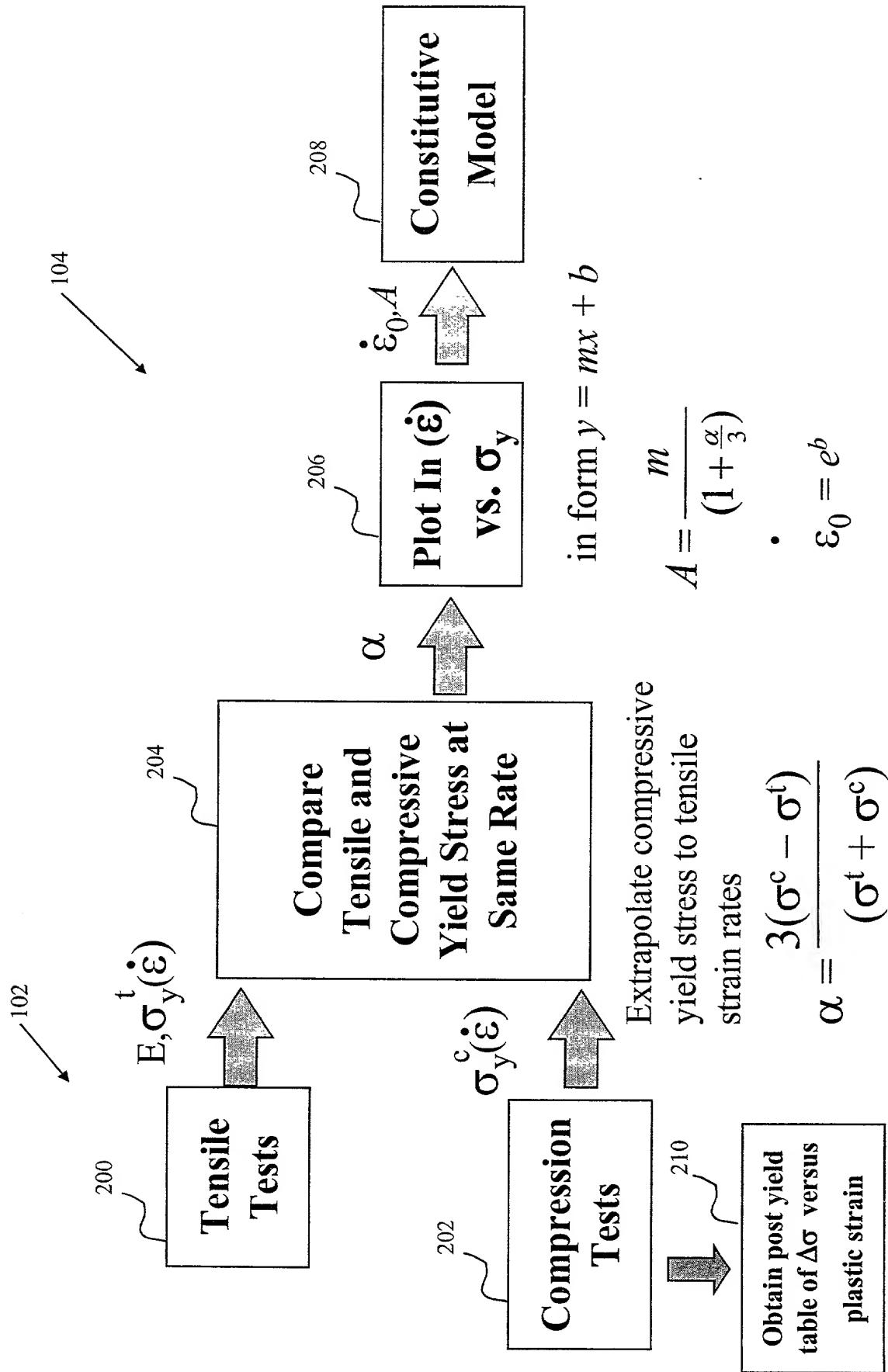


FIG. 13

source code implicit finite element solver

```
c      rate/temp/press dependent, von mises isotropic plasticity
c      umat for abaqus 5.5. nonlinear strain hardening.
c      2d/3d problems with the exception of plane stress
c      by omar a hasan      last modified 05-02-96
c      user must specify differential hardening data in umat
c      and dimension hardening table appropriately
c      must have atleast two sets of points in table
c      subroutine umat(stress,statev,ddsdde,ss,e,spd,scd,
1 rpl,ddsdde,drplde,drpldt,
2 stran,dstran,time,dtime,temp,dtemp,predef,dpred,cmname,
3 ndi,nshrtens,nstatv,props,nprops,coords,drot,pnewdt,
4 celent,dfgrd0,dfgrdl,noel,npt,layer,kspt,kstep,kinc)
c
c      include 'aba_param.inc'
c
c      character*8 cmname
c      dimension stress(ntens),statev(nstatv),
1 ddsdde(ntens,ntens),ddsdde(ntens,ntens),drplde(ntens),
2 stran(ntens),dstran(ntens),time(2),predef(1),pred(1),
3 props(nprops),coords(3),drot(3,3),dfgrd0(3,3),dfgrdl(3,3)
c
c      dimension flow(b)
c
c      parameter(zero=0.d0,one=1.d0,two=2.d0,three=3.d0,six=6.d0,
1 newton=60,toler=1.0d-5,twbth=0.66666666666d0)
c -----
c      cannot be used for plane stress
c -----
c      props(1) - e (Pa) (temperature dependent)
c      props(2) - nu
c      props(3) - rate sensitivity (temperature dependent)
c      props(4) - intrinsic flow rate (temperature dependent)
c      props(5) - pressure sensitivity
c      calls uhard for curve of intrinsic strength vs. plastic strain
c -----
c      material properties
c      emod=props(1)
c      enu=props(2)
c      ebulk3=emod/(one-two*enu)
c      eg2=emod/(one+enu)
c      eg=eg2/two
c      eg3=three*eg
c      elam=(ebulk3-eg2)/three
c      rlp2m=elam+eg2/three
c      ratesf=props(3)
c      rrates=one/ratesf
c      dtebs0=dtime*props(4)
```

FIG 14A

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source code implicit finite element solver

```
psf=props(5)
esi=dstran(1)**2+dstran(2)**2+dstran(3)**2
do kl=ndi+1,ntens
  esi=esi+two*(dstran(kl)/two)**2
end do
esi=sqrt(twbth*esi)
s_rate=max(1.d-10,esi/dtime)

c elastic stiffness
call aset(ddsdde,zero,ntens*ntens)
do kl=1,ndi
  do k2=1,ndi
    ddsdde(k2,kl)=elam
  end do
  ddsdde(kl,kl)=eg2+elam
end do
do kl=ndi+1,ntens
  ddsdde(kl,kl)=eg
end do

c recover equivalent plastic strain & equivalent stress
c and hydrostatic stress at start of step
eqplas=statev(1)
qold=statev(2)
hydr_o=(stress(1)+stress(2)+stress(3))/three

c calculate predictor stress
do kl=1,ntens
  do k2=1,ntens
    stress(k2)=stress(k2)+ddsdde(k2,kl)*dstran(kl)
  end do
end do

c calculate equivalent von mises stress
c
smises=(stress(1)-stress(2))**2+(stress(2)-stress(3))**2
l           +(stress(3)-stress(1))**2
do kl=ndi+1,ntens
  smises=smises+six*stress(kl)**2
end do
smises=sqrt(smises/two)

c get differential hardening from the specified hardening curve
call uhard(syiel0,hard,eqplas)

c determine if actively yielding
if (time(1).gt.0.d0) then

c separate the hydrostatic from the deviatoric stress
calculate the flow direction
```

FIG 14B

source code implicit finite element solver

```
shydro=(stress(1)+stress(2)+stress(3))/three
do k1=1,ndi
  flow(k1)=(stress(k1)-shydro)/smises
end do
do k1=ndi+1,ntens
  flow(k1)=stress(k1)/smises
end do

c
c  solve for equivalent von mises stress
c  and equivalent plastic strain increment using newton iteration
on
  syield=syield0
c  use this to minimize iterations during elastic deformation (
1)
  deqpl=dtebs0*exp((smises-syield)*ratesf)
c  use this to minimize iterations during plastic deformation (
2)
  deqpl=esi
  do kewton=1,newton
    deqpl=max(deqpl,1.d-50)
    qhs=smises-eg3*deqpl-syield-rrates*dlog(deqpl/dtebs0)
    rhs=qhs+psf*shydro
    deqpl=deqpl+deqpl*rhs/(deqpl*(eg3+hard)+rrates)
    call uhard(syield,hard,eqplas+deqpl)
    if(abs(rhs).lt.toler*60.d0) goto 10
  end do
  write(7,2) newton
  2  format(//,30x,'***warning - plasticity algorithm did not
    'converge after ',i3,' iterations')
  write(7,*)dstran(1),dstran(2),dstran(3),dstran(4)
  write(7,*)dstran(5),dstran(6),esi,smises,statev(1)
  write(7,*)statev(2),statev(3),statev(4),statev(5)
  write(7,*)qhs,deqpl,rhs,shydro,stress(1),stress(2)
  write(7,*)stress(3),stress(4),stress(5),stress(6)
  10 continue
c
c  the new equivalent deviatoric stress (q) is
  q=syield+rrates*dlog(deqpl/dtebs0)-psf*shydro
c
c  update stress, elastic and plastic strains and
c  equivalent plastic strain
  do k1=1,ndi
    stress(k1)=flow(k1)*q+shydro
  end do
  do k1=ndi+1,ntens
    stress(k1)=flow(k1)*q
  end do
  eqplas=eqplas+deqpl
c
```

FIG. 14C

source code implicit finite element solver

```
c calculate plastic dissipation
  spd=deqpl*(qold+q)/two
c
c formulate the jacobian (material tangent)
c first calculate effective moduli
  effg=eg*q/smises
  effg2=two*effg
  effg3=three/two*effg2
  efflam=(ebulk3-effg2)/three
  hardl=hard+rates/deqpl
  effhrd=eg3*hardl/(eg3+hardl)-effg3
  cee=-ebulk3*psf*eg*deqpl/smises
  do k1=1,ndi
    do k2=1,ndi
      ddsdde(k2,k1)=efflam+cee*flow(k2)
    end do
    ddsdde(k1,k1)=effg2+efflam+cee*flow(k1)
  end do
  do k1=ndi+1,ntens
    ddsdde(k1,k1)=effg
  end do
  do k1=1,ntens
    do k2=1,ntens
      ddsdde(k2,k1)=ddsdde(k2,k1)+effhrd*flow(k2)*flow(k1)
    end do
  end do
  endif
c
c store state variables in array
c equiv strain,mises stress,plastic strain rate,elastic strain
c rate and iterations to convergence
  statev(1)=eqplas
  statev(2)=q
  statev(3)=deqpl/dtime
  statev(4)=esi/dtime
  statev(5)=kewton
c
  return
end
c
subroutine uhard(syield,hard,eqplas)
c
  include 'aba_param.inc'
c table must be dimensioned correctly below:
  dimension table(2,7)
  parameter(zero=0.d0)
c nbv 313 hardening table
  nvalue=7
c   this is room temp data
  table(1,1)=0.00d0
```

FIG. 14D

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source code implicit finite element solver

```
table(2,1)=0.0
table(1,2)=-5.295d0
table(2,2)=0.151
table(1,3)=-3.04d0
table(2,3)=0.337
table(1,4)=4.726d0
table(2,4)=0.542
table(1,5)=14.41d0
table(2,5)=0.736
table(1,6)=48.146d0
table(2,6)=1.093
table(1,7)=2704.4d0
table(2,7)=17.086
c
do kl=1,nvalue-1
  eqpl1=table(2,kl+1)
  if(eqplas.lt.eqpl1) then
    eqpl0=table(2,kl)
    current yield stress and hardening
  c
    deqpl=eqpl1-eqpl0
    syiel0=table(1,kl)
    syiel1=table(1,kl+1)
    dsyiel=syiel1-syiel0
    hard=dsyiel/deqpl
    syield=syiel0+(eqplas-eqpl0)*hard
    goto 10
  endif
end do
10  continue
c
return
end
```

FIG. 14E

source code explicit finite element solver

```
c      vectorized user material subroutine for shell and plane
c      stress elements (abaqus5.5)
c      rate/temp dependent isotropic plasticity with linear
c      elasticity, strain softening/hardening & press. depnd.
c      yield
c      by omar a hasan (hasan@crd.ge.com)
c      last modified 05-03-96
c
c      subroutine vumat(
c      read only variables (unmodifiable)
1      nblock,ndir,nshri,nstatev,nfieldv,nprops,lanneal,
2      step_time,total_time,dt,cmname,coord_mp,char_length,
3      props,density,strain_inc,rel_spin_inc,
4      temp_old,stretch_old,defgrad_old,field_old,
5      stress_old,state_old,ener_intern_old,ener_inelas_old,
6      temp_new,stretch_new,defgrad_new,field_new,
c      write only variables (modifiable)
7      stress_new,state_new,ener_intern_new,ener_inelas_new)
c
c      include 'vaba_param.inc'
c
c      dimension coord_mp(nblock,*),char_length(nblock),props(npro
ps),
1      density(nblock),strain_inc(nblock,ndir+nshri),
2      rel_spin_inc(nblock,nshri),temp_old(nblock),
3      stretch_old(nblock,ndir+nshri),
4      defgrad_old(nblock,ndir+nshri+nshri),field_old(nblock,nfieldv
),
5      stress_old(nblock,ndir+nshri),state_old(nblock,nstatev),
6      ener_intern_old(nblock),ener_inelas_old(nblock),
7      temp_new(nblock),stretch_new(nblock,ndir+nshri),
8      defgrad_new(nblock,ndir+nshri+nshri),field_new(nblock,nfieldv
),
9      stress_new(nblock,ndir+nshri),state_new(nblock,nstatev),
1      ener_intern_new(nblock),ener_inelas_new(nblock)
c
c      integer limit
c      parameter (limit=40)
c      dimension table(2,9)
c      character*8 cmname
c      parameter(zero=0.d0,one=1.d0,two=2.d0,three=3.d0,six=6.d0,
1      four=4.d0,oneptf=1.5d0,zept=0.25d0,twbth=0.6666666666d0,
2      eitee=80.d0)
c
c -----
c      props(1) - e- modulus (temperature dependent)
c      props(2) - nu- poisson ratio
c
c      Properties 3 and 4 describe the rate sensitivity of yield ba
sed on a plot of
```

FIG 15A

source code explicit finite element solver

```
c      yield stress (x-axis) vs ln(strain rate) y-axis
c
c      props(3) - rate sensitivity (temperature dependent)  SLOPE
c      props(4) - intrinsic flow rate (temperature dependent)INTER
CPT
c
c      Property 5 describes the pressure sensitivity of yield
c
c      props(5) - pressure sensitivity factor
c
c      Property 6 is the failure criterion ... either an equivalent
c      plastic strain
c      for ductile failure or a maximum principal stress for brittle
c      failure
c
c      props(6) - failure criterion
c
c      NOTE -THESE FOLLOWING TWO LINES WOULD APPEAR IN THE ABAQUS
EXPLICIT
c      INPUT DECK
c
c      *USER MATERIAL,CONSTANTS=5
c      2.24e9,0.40,3.29e-7,1.48e-14,0.16
c      *DEPVAR,DELETE=6
c      8
c -----
c
c      material properties
emod=props(1)
enu=props(2)
ebulk3=emod/(one-two*enu)
eg2=emod/(one+enu)
eg=eg2/two
eg3=three*eg
elam=(ebulk3-eg2)/three
elp2g=elam+eg2
ratesf=props(3)
dtebs0=dt*props(4)
psf=props(5)
rrates=one/ratesf
failst=props(6)
table(1,1)=0.0
table(2,1)=0.0
table(1,2)=6.2
table(2,2)=0.15
table(1,3)=17.93
table(2,3)=0.35
table(1,4)=34.47
table(2,4)=0.55
table(1,5)=53.09
```

FIG 15B

source code explicit finite element solver

```
table(2,5)=0.75
table(1,6)=70.32
table(2,6)=0.95
table(1,7)=91.01
table(2,7)=1.15
table(1,8)=146.16
table(2,8)=1.35
table(1,9)=201.3
table(2,9)=1.55
c
do 100 i=1,nblock
c
c initialize state variables
eqplas=state_old(i,1)
sm_old=state_old(i,2)
icont=state_old(i,3)
tstart=total_time-dt
if (tstart.lt.1.e-6) then
icont=1
state_old(i,6)=one
endif
c
if (state_old(i,6).lt.0.5) then
state_new(i,6)=zero
goto 100
endif
c
c get hardening modulus and intrinsic resistance at t
hard=(table(1,icont+1)-table(1,icont))/  
1 (table(2,icont+1)-table(2,icont))
s_intr=table(1,icont)+hard*(eqplas-table(2,icont))
c
c calculate predictor stress
trace2=strain_inc(i,1)+strain_inc(i,2)
del_e33=-elam*trace2/elp2g
sig11o=stress_old(i,1)+eg2*strain_inc(i,1)
sig22o=stress_old(i,2)+eg2*strain_inc(i,2)
sig33=zero
sig12=stress_old(i,4)+eg2*strain_inc(i,4)
ssl2s=six*(sig12**2)
c
since strain_inc(i,3) is not known apriori, loop 3
times without checking for convergence (works very well
c in practise by reducing sig33 to 0.0000001*syield)
do 200 ii=1,3
trace=trace2+del_e33
sig11=sig11o+elam*trace
sig22=sig22o+elam*trace
c
calculate equivalent von mises stress from deviatoric
```

FIG. 15C

source code explicit finite element solver

```
c      component of trial (predictor) stress.
smises=(sig11-sig22)**2+(sig22)**2+(sig11)**2
smises=smises+ssl2s
smises=sqrt(smises/two)
c      avoid division by zero during first iteration
smises=max(one,smises)
c
c      separate the hydrostatic from the deviatoric stress
c      calculate the flow direction
shydro=(sig11+sig22)/three
flow11=(sig11-shydro)/smises
flow22=(sig22-shydro)/smises
flow33=(sig33-shydro)/smises
flow12=sig12/smises

c
c      solve for equivalent von mises stress and equivalent
c      plastic strain increment
adfp=-psf*shydro*ratesf
deqpl=dtebs0*exp((sm_old-s_intr)*ratesf+adfp)
sm_new=smises-eg3*deqpl

c
c      update e33
opfe=oneptf*deqpl
d_epl1=opfe*flow11
d_ep22=opfe*flow22
d_ep33=opfe*flow33
d_epl2=opfe*flow12
d_eel11=strain_inc(i,1)-d_epl1
d_ee22=strain_inc(i,2)-d_ep22
d_ee33=-elam*(d_eel11+d_ee22)/elp2g
d_eel2=strain_inc(i,4)-d_epl2
del_e33=d_ee33+d_ep33
200  continue
esi=strain_inc(i,1)**2+strain_inc(i,2)**2+
1  del_e33**2+two*strain_inc(i,4)**2
esi=sqrt(esitwbth)
strain_inc(i,3)=del_e33

c
c      update stress, equivalent plastic strain, location
c      of plastic strain counter and state variables
stress_new(i,1)=flow11*sm_new+shydro
stress_new(i,2)=flow22*sm_new+shydro
stress_new(i,3)=zero
stress_new(i,4)=flow12*sm_new
eqplas=eqplas+deqpl
if (eqplas.gt.table(2,icont+1)) icont=icont+1
cstate_new(i,1)=state_old(i,1)+d_eel1
cstate_new(i,2)=state_old(i,2)+d_ee22
cstate_new(i,3)=state_old(i,3)+d_eel2
cstate_new(i,4)=state_old(i,4)+d_epl1
```

FIG. 15D

source code explicit finite element solver

```
cstate_new(i,5)=state_old(i,5)+d_ep22
cstate_new(i,6)=state_old(i,6)+d_ep12
c save state variables: plastic strain, vm stress,, total
c strain rate, plastic strain rate, failure criterion flag
state_new(i,1)=eqplas
state_new(i,2)=sm_new
state_new(i,3)=icont
state_new(i,4)=esi/dt
state_new(i,5)=deqpl/dt
state_new(i,6)=state_old(i,6)
c
bee=-(stress_new(i,1)+stress_new(i,2))
bee2=bee*bee
cee=stress_new(i,1)*stress_new(i,2)-stress_new(i,4)*
1 stress_new(i,4)
froot=bee2-four*cee
ffrot=max(one,froot)
sqbm4c=sqrt(ffrot)
pmax=(-bee+sqbm4c)/two
pmin=(-bee-sqbm4c)/two
state_new(i,7)=pmax
state_new(i,8)=pmin
c UNPAINTED
failst=89.0b
if (pmax.gt.failst) state_new(i,6)=zero
strain based failure criterion
if (eqplas.gt.failst) state_new(i,6)=zero
c update plastic dissipation
plastic_work_inc=deqpl*(sm_old+sm_new)/two
ener_inelas_new(i)=ener_inelas_old(i)+
1 plastic_work_inc/density(i)
c
100 continue
return
end
```

FIG 15E